

MIDTERM, DIFFERENTIAL GEOMETRY  
DUE 3/24/17

**Problem 1. The Frenet frame of a curve in  $\mathbb{R}^3$ .** For a regular plane curve (and more generally for a regular curve on a 2-dimensional surface - e.g. the 2-sphere above) we could construct a unique adapted frame  $F$ . This is not the case for curves in higher dimensional spaces. Besides the curve being regular we need more conditions to ensure the existence of a unique adapted frame, which then will give invariants of the curve, which in turn reconstruct the curve up to Euclidean motions.

Let  $\gamma: I \rightarrow \mathbb{R}^3$  be an arclength parametrized curve. Then  $T = \gamma'$  has unit length.

- (i) Show that  $\langle \gamma'', T \rangle = 0$ . Thus, provided that  $\gamma''$  is nowhere vanishing, we can define  $N := \gamma'' / \|\gamma''\|$  and obtain a moving basis  $\{T, N, T \times N\}$ . A regular space curve for which  $\gamma''$  is nowhere vanishing is called a *Frenet curve*. From now on we assume that we have this property.
- (ii) Let  $\gamma$  be an arclength parametrized Frenet curve. Define the curvature function to be  $\kappa := \|\gamma''\| > 0$  and the *torsion* function  $\tau := \langle T \times N, N' \rangle$ . Show that the adapted frame  $F = (T, N, T \times N): I \rightarrow \mathbf{SO}(3, \mathbb{R})$  and calculate  $A = F^{-1}F'$  in terms of  $\kappa$  and  $\tau$ . This is just a more compact formulation of the following: calculate  $T'$  and express it in the basis  $\{T, N, T \times N\}$ ; then do the same for  $N'$  and  $(T \times N)'$ . You can save yourself computations by using that  $\{T, N, T \times N\}$  is an orthonormal basis for each  $t \in I$  and look up HW 5 Problem 1.
- (iii) If  $\gamma$  is an arclength parametrized planar curve, we can regard it as a space curve. Show that this space curve has  $\tau \equiv 0$ . Also prove the converse: if a space curve has  $\tau \equiv 0$  then it lies in some plane  $P \subset \mathbb{R}^3$ .
- (iv) Show that given functions  $\kappa: I \rightarrow \mathbb{R}$ ,  $\kappa(t) > 0$  for all  $t \in I$ , and  $\tau: I \rightarrow \mathbb{R}$  both smooth, there exists a unique (up to Euclidean motion) Frenet curve in  $\mathbb{R}^3$  whose curvature and torsion are  $\kappa$  and  $\tau$  respectively.
- (v) Classify all the Frenet space curves which have curvature and torsion constant.

**Problem 2.** Let  $\gamma: I \rightarrow S^2$  be a regular curve in the 2-sphere. We have discussed (in HW 5 Problem 2) its curvature, which we shall call for now *geodesic curvature* (to not get confused with the curvature this curve may have as a curve in  $\mathbb{R}^3$ ) and label it as  $\kappa_g$ .

- (i) Regarding the curve  $\gamma$  as a space curve  $S^2 \subset \mathbb{R}^3$ , and assuming it to be Frenet, calculate its curvature  $\kappa$  and torsion  $\tau$  in terms of  $\kappa_g$ .
- (ii) State and prove necessary and sufficient conditions for a Frenet curve  $\gamma: I \rightarrow \mathbb{R}^3$  to be contained in some 2-sphere  $S = \{x \in \mathbb{R}^3; \|x - c\| = r\}$  of center  $c$  and radius  $r > 0$ .

**Problem 3.** Find all the critical points (under compactly supported variations) for the length functional

$$L(\gamma) = \int_I \|\gamma'(t)\| dt$$

on regular curves  $\gamma: I \rightarrow \mathbb{R}^n$  in any dimension  $n$ . Since there is no notion of curvature for  $n \geq 4$  (at least we did not discuss that) you will just have to leave the term  $\gamma''$  in the variational calculus and try to find the conditions  $\gamma$  has to satisfy to be a critical point.

**Problem 4.** Consider the energy functional

$$E(\gamma) = \int_I \|\dot{\gamma}(t)\|^2 dt$$

on regular curves  $\gamma: I \rightarrow S^2$ .

- (i) Show that if  $\gamma_s: I \rightarrow S^2$  is any variation of  $\gamma = \gamma_0$  by curves on  $S^2$  then its variational vector field  $V = \dot{\gamma}$  satisfies  $\langle V, \dot{\gamma} \rangle = 0$ .
- (ii) Let  $V: I \rightarrow \mathbb{R}^3$  be smooth with  $\langle V, \dot{\gamma} \rangle = 0$ . Show that there is a variation  $\gamma_s$  of  $\gamma$  by curves on  $S^2$ . Moreover, if  $V$  is compactly supported so will be  $\gamma_s$ .
- (iii) Characterize the critical points of  $E$  under compactly supported variations  $\gamma_s$  by curves on  $S^2$ .
- (iv) If the curve  $\gamma$  were simply closed, it would define an enclosed area (modulo  $4\pi$  – one has two areas for a simply closed curve on the 2-sphere). Characterize area constrained  $E$  critical curves  $\gamma$ . Using the Lagrange multiplier approach what is the functional  $\tilde{E} = E + \lambda A$ ? you will work with? You will need to find an expression of the enclosed area in terms of  $\gamma$ .