

1(a) Let $F: V \rightarrow W$ be linear. $\ker(F) = \{v \in V \mid F(v) = 0\}$.

$\text{im}(F) = \{w \in W \mid \text{there exists } x \in V \text{ so that } F(x) = w\}$.

(c). $S \subseteq V$ is a subspace \iff (i) $x, y \in S \Rightarrow x+y \in S$, and

(ii) $x \in S, \lambda \in \mathbb{R} \Rightarrow \lambda x \in S$.

(d). $\dim V$ equals the number of elements in a basis of V . If there is no finite basis of V we say the dimension is infinite.

2:
$$\begin{pmatrix} 1 & -1 & 1 & -1 & 1 \\ 2 & 1 & 0 & -1 & 1 \\ 7 & -1 & 3 & -5 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 3 & -2 & 1 & -1 \\ 0 & 6 & -4 & 2 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 3 & -2 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 1 & -2/3 & 1/3 & -1/3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1/3 & -2/3 & 2/3 \\ 0 & 1 & -2/3 & 1/3 & -1/3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$x_1 = -1/3 x_3 + 2/3 x_4 - 2/3 x_5$

$x_2 = 2/3 x_3 - 1/3 x_4 + 1/3 x_5$

$x_3 = x_3$

$x_4 = x_4$

$x_5 = x_5$

$$\therefore \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = x_3 \begin{pmatrix} -1/3 \\ 2/3 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \\ 1 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -2/3 \\ 1/3 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Conclude: $\left\{ \begin{pmatrix} -1/3 \\ 2/3 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2/3 \\ -1/3 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2/3 \\ 1/3 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ is a basis of $\ker F$

and $\left\{ \begin{pmatrix} 1 \\ 2 \\ 7 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} \right\}$ is a basis of $\text{im}(F)$. The rank of F is 2

3. If $A = \left\{ \begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right\}$. Then $f_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}_A \rightsquigarrow \begin{pmatrix} 1 \\ 3 \end{pmatrix}_E$
 $f_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}_A \rightsquigarrow \begin{pmatrix} 1 \\ 2 \end{pmatrix}_E$

$\therefore \mathbb{1}_{E \leftarrow A} = \begin{pmatrix} 1 & 1 \\ 3 & 2 \end{pmatrix}$ and (This is 3b)

$\mathbb{1}_{A \leftarrow E} = \frac{1}{-1} \begin{pmatrix} 2 & -1 \\ -3 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 3 & -1 \end{pmatrix}$ (This is 3a)

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3c. $v_E = \begin{pmatrix} 1 \\ -2 \end{pmatrix} \Rightarrow v_A = \frac{1}{A \leftarrow E} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \begin{pmatrix} -4 \\ 5 \end{pmatrix}_A$

3d. $M_{A \leftarrow A} = \begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \text{L.T.S.}$

4. $2x - y + z = 0$ is the plane thru the origin \perp to $(2, -1, 1)$. We find a basis of this plane. That is, we find a basis of the kernel of linear map associated to matrix $M = \begin{pmatrix} 2 & -1 & 1 \end{pmatrix}$. Setting

$y=1, z=0$ we get $x = -1/2$ so $\begin{pmatrix} -1/2 \\ 1 \\ 0 \end{pmatrix} \in \text{kernel of } M$

Set $y=0, z=1$ we get $x = -1$ so $\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \in \text{kernel of } M$.

Since these two vectors ~~are~~ ^{are} in P we have $R \begin{pmatrix} -1/2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 1 \\ 0 \end{pmatrix}$

$R \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1/2 \\ 0 \\ 1 \end{pmatrix}$. We have $R \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$, let these three

vectors be our basis. Then the matrix is $\begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ (suitably order these vectors).

5(a). True. [Let M be the matrix with columns v_1, \dots, v_n . Then $\ker(M) = 0 \Rightarrow$ (by rank-nullity) $\text{rank} = n = \dim \text{im}(M)$

But \mathbb{R}^n is only subspace of \mathbb{R}^n with $\dim n$. $\therefore \text{im}(M) = \mathbb{R}^n$.

[This says $\text{span of } v_1, \dots, v_n \text{ is all of } \mathbb{R}^n$] OR (better). Let W be subspace spanned by $\{v_1, \dots, v_n\}$. It is $\dim \geq n$; thus it has to be \mathbb{R}^n .

(b) False: The image is spanned by the column vectors. Thus any basis of the image has ≤ 4 elts, but $\dim \mathbb{R}^5 = 5$.

(c) True: $2u + 3v + 4w = 3u - 4v + 5w \Rightarrow$
 $0 = u - 7v + w$.

This is a non-trivial linear relation among $\{u, v, w\}$. Thus this set of vectors is linearly dependent.

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5d. False: $\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$.

(6) (a) It is a subspace! (a) let $f, g \in S$, so $\frac{df}{dt}(t) = f(t)$

and $\frac{dg}{dt}(t) = g(t)$. ~~Then~~ $\frac{d}{dt}(f+g)(t) = \frac{df}{dt}(t) + \frac{dg}{dt}(t)$

hypothesis $\Rightarrow f(t) + g(t) = (f+g)(t)$.

(b) let $f \in S$, $\lambda \in \mathbb{R}$, so $\frac{df}{dt}(t) = f(t)$.

Then $\frac{d}{dt}(\lambda f)(t) = \lambda \frac{df}{dt}(t) = \lambda f(t) = (\lambda f)(t)$.
 \therefore yes S is a subspace. \uparrow hypothesis

(b) The set of all 3×3 invertible matrices is Not a subspace.

For example $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

(c) Let $v = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$. The set of 3×3 matrices A so that $Av = 0$ is a

subspace of $\mathbb{R}^{3 \times 3}$: (a) Assume $Av = 0$, $Bv = 0$. Then

$(A+B)v = Av + Bv = 0 + 0 = 0$.

(b) Assume $Av = 0$, then $(\lambda A)v = \lambda(Av) = \lambda \cdot 0 = 0$.

(d) In 6a find a basis of S . let $f = at^2 + bt + c$. ~~Then~~

~~$f(t) = a + b + c$
 $\frac{df}{dt} = 2at + b$
 $\left. \frac{df}{dt} \right|_{t=2} = 4a + b$~~

~~Then $f \in S \Leftrightarrow a + b + c = 0$ and $4a + b = 0$. let $M = \begin{pmatrix} 1 & 1 & 0 \\ 4 & 1 & 0 \end{pmatrix}$.~~

~~Find $\ker M$ basis for $\ker M$. $\therefore \frac{df}{dt} = 2at + b$ $\left. \frac{df}{dt} \right|_{t=1} = 2a + b$~~

$f(t) = 4a + 2b + c \therefore$ We are looking for a, b, c so that

$4a + 2b + c = 2a + b \therefore$ looking for solutions to $2a + b + c = 0$.

This is kernel of matrix $\begin{pmatrix} 2 & 1 & 1 \end{pmatrix}$. L.T.S.

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7a. $\mathbb{R}^{m \times n}$ has dim $m \cdot n$. A basis consists of the matrices with all zero entries ~~and~~ except 1 position. In that position put a 1. There are $m \cdot n$ positions.

7b. P_n has dim $n+1$. A basis is $\{1, t, \dots, t^n\}$.

7c. \mathbb{C}^2 has dim 4. A basis is $\{(1,0), (i,0), (0,1), (0,i)\}$

7d. $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ $AB = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} a & a+b \\ c & c+d \end{pmatrix}$

$BA = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+c & b+d \\ c & d \end{pmatrix}$.

$AB = BA \Leftrightarrow c = 0 \wedge a = d$. ~~$c = 0$~~

Thus A commutes with $B \Leftrightarrow$ it is of the form

$\begin{pmatrix} a & b \\ 0 & a \end{pmatrix}$. ~~This has basis~~ This set of such matrices

has a basis $\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right\}$. Thus dimension is 2.

8. 8a. $T: M \rightarrow M^2$ is not linear, since $T(\lambda M) = \lambda^2 T(M)$

8b. $M \rightarrow \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} M$ is linear, ~~It is an isomorphism.~~ It has an inverse:

$M \rightarrow \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}^{-1} \cdot M$. You need to say ~~that~~ why $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

has an inverse. For example it has two leading ones when row reduced, OR the det is $\neq 0$.

8c. $T: x+iy \rightarrow x$. This is linear. It is not an isomorphism. For example $T(2i) = 0$.

8d. $T: x+iy \rightarrow (3+4i)(x+iy)$ is an isomorphism.

It has an inverse: $\frac{1}{5}(3-4i)$.

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8e. $T: \mathcal{P} \rightarrow \mathcal{P}'' - 3\mathcal{P}'$ $\mathcal{P} \in \mathcal{P}_2$ is linear. It is not an isomorphism since $T(1) = 0$.

8f. $T: at^2+bt+c \rightarrow (2a) - 3(2at+b) = -6at + (2a-3b) = 0$
 $\Leftrightarrow a=0$ and $2a-3b=0 \Rightarrow \overset{a=0}{\cancel{a=b}}$ and $b=0$.

$\therefore \text{Im } T = \{c \cdot 1 \mid c \in \mathbb{R}\}$ \therefore A basis for $\text{Im } T$ is the function 1.

8g. $T: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$ is an isomorphism.
 \therefore nullity = 0 and rank = 4.

9a. $T: M \rightarrow M \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} M$

$\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \rightarrow \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} = \begin{pmatrix} a & -2a+b \\ 0 & c \end{pmatrix} - \begin{pmatrix} a & b+c \\ 0 & c \end{pmatrix}$
 $= \begin{pmatrix} 0 & -2a+b-c \\ 0 & 0 \end{pmatrix}$ $\therefore \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & -2 \\ 0 & 0 \end{pmatrix} = -2 \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$
 $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = 1 \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$
 $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix} = 1 \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$

\therefore matrix of T

is $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -2 & 1 & 1 \end{pmatrix}$. This is not an isomorphism.

(Use row reduction) $\rightarrow \begin{pmatrix} 1 & -1/2 & -1/2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ \therefore kernel in basis B has

basis $\left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}_B, \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}_B \right\} \rightarrow \left\{ \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \right\}$

The image is spanned by $\begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix}_B \rightarrow \begin{pmatrix} 0 & -2 \\ 0 & 0 \end{pmatrix}$.

9b. $T: x+iy \rightarrow x-iy$

$1 \rightarrow 1$ in terms of basis $C = \{1, i\}$ this

$i \rightarrow -i$

has matrix $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$. It is an isomorphism.

9c. $x+iy \rightarrow (4-bi)(x+iy)$

$1 \rightarrow 4-bi$

$i \rightarrow 6+4i$

or in terms of basis C

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}_C \rightarrow \begin{pmatrix} 4 \\ -b \end{pmatrix}_C$

$\begin{pmatrix} 0 \\ 1 \end{pmatrix}_C \rightarrow \begin{pmatrix} 6 \\ 4 \end{pmatrix}_C$

$\therefore T \leftrightarrow \begin{pmatrix} 4 & b \\ -b & 4 \end{pmatrix}_C$. This is an isomorphism.

9d. $T: P_2 \rightarrow P_2$

$f \mapsto f' + 3f$

$1 \rightarrow 0 + 3 \cdot 1$

$t \rightarrow 1 + 3t$

$t^2 \rightarrow 2t + 3t^2$

$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$

$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$

$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix}$

$\therefore T$ corresponds to the matrix $\begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 2 \\ 0 & 0 & 3 \end{pmatrix}_{A \leftarrow A}$.

It has 3 leading ones when row reduced, hence it is an isomorphism.

9e. $T: P_2 \rightarrow \mathbb{R}$

$f \mapsto f(3)$

$1 \mapsto 1$

$t \mapsto 3$

$t^2 \mapsto 9$

$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow 1$

$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rightarrow 3$

$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow 9$

$\therefore (1 \ 3 \ 9) \Rightarrow T$ using our bases.

10. $F: V \rightarrow V$

$f \mapsto f(3x) + 2f(x)$

Is F linear? $(F(f+g))(x) =$

$(f+g)(3x) + 2(f+g)(x) = f(3x) + 2f(x) + g(3x) + 2g(x) = Ff + Fg$

(b) $(F(\lambda f))(x) = (\lambda f)(3x) + 3(\lambda f)(x)$

$= \lambda f(3x) + 3(\lambda f(x)) = \lambda(f(3x) + 3f(x)) = \lambda(F(f))(x)$

Yes. It is linear.

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10b. Let $G: V \rightarrow V$ be given by $f(x) \rightarrow f'(x) + 5f(x)$.

This is linear, (a) $G(f+g)(x) = (f+g)'(x) + 5(f+g)(x)$
 $= f'(x) + g'(x) + 5(f(x) + g(x)) = G(f)(x) + G(g)(x)$.

(b). $G(\lambda f)(x) = (\lambda f)'(x) + 5(\lambda f)(x)$
 $= \lambda f'(x) + 5 \cdot \lambda f(x) = \lambda(Gf)(x)$. Done.